

# States and Actions: An Automata-theoretic Model of Objects

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# Outline

- 1 Information Hiding
- 2 States and actions
- 3 Examples
- 4 Semantic Overview
- 5 Conclusion

# What it is about

Study the semantics of imperative object-oriented programming, using Idealized Algol as the foundational language.

- Can we bridge the gap between the state-based paradigm (Scott-Strachey approach) of semantics and the event-based paradigm (Milner-Hoare approach)?
- What is the right notion of *relational parametricity* (capturing data abstraction) for programs manipulating store?
- Can we push the full abstraction results *beyond the second-order active types* of Idealized Algol?

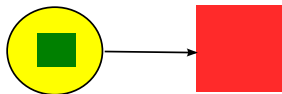
Reynolds [1981] anticipates many of these ideas.

# Section 1

## Information Hiding

# Information hiding

- Imperative programs have information hiding pretty much everywhere.
- Object-oriented programming exploits this information hiding.



- Information hiding arises much more fundamentally:
  - when local variables are declared (hidden outside their declaring blocks),
  - when procedures are called (data in the calling context hidden from the procedure)
- As a result of information hiding, we get:
  - reasoning principles based on **invariants** (useful for proving properties, safety, consistency, integrity),
  - reasoning principles based on **simulation relations** (useful for program equivalence and data refinement).

# Information hiding leads to Invariants

- Consider:

$$\begin{array}{l} \mathbf{while} \ x \leq 100 \ \mathbf{do} \\ \quad x := x + 1 \end{array}$$

- $x \geq 0$  is invariant in  $x := x + 1$ .
- Hence,  $x \geq 0$  is invariant in the entire while-loop.

$$\frac{\{P\} C \{P\}}{\{P\} \mathbf{while} B \ \mathbf{do} C \{P\}}$$

- This invariant principle has nothing to do with while-loops as such. It also applies to *all* primitive control structures (repeat-until, for-loops, if-then-else etc.)

$$\frac{\{P\} C_1 \{P\} \quad \{P\} C_2 \{P\}}{\{P\} \mathbf{if} B \ \mathbf{then} C_1 \ \mathbf{else} C_2 \{P\}}$$

## Information hiding leads to Invariants - 2

- The same principle also applies to user-defined higher-order procedure constants (with no free identifiers)  $F : \mathbf{comm} \rightarrow \mathbf{comm}$ :

$$\frac{\{P\} C \{P\}}{\{P\} F(C) \{P\}}$$

We don't even have to know what  $F$  does to establish the invariant principle!

- Why do these principles work?
- Answer: Information hiding.
- **while** is a constant (no free identifiers) of type:

**while** :  $\mathbf{exp}[\mathbf{bool}] \times \mathbf{comm} \rightarrow \mathbf{comm}$

The action of **while** has no direct access to any storage, other than what is provided by its arguments.

- Hence, any property left invariant by the arguments is also left invariant by the **while** loop.
- The storage of the arguments is *hidden from the while*

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# Information hiding leads to binary simulation relations

- Consider a relation:

$$x [R] y \iff y = -x$$

- Notice:

$$\begin{aligned} x \leq 100 [R_{\text{exp[bool]}}] y \geq -100 \\ (x := x + 1) [R_{\text{comm}}] (y := y - 1) \end{aligned}$$

- Infer

**while**  $x \leq 100$  **do**  $x := x + 1$   
     $[R_{\text{comm}}]$   
**while**  $y \geq -100$  **do**  $y := y - 1$

- Again, it is not necessary to know what **while** does, in order to infer this fact.
- Every constant combinator will preserve the binary simulation relation in the same way (including user-defined combinators).

# Information hiding in OOP

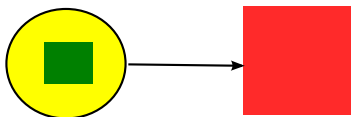
- The same ideas also work for O-O classes.

```
class  
  local Var[int] x;  
  init x := 0;  
  meth  
    { val() = x,  
      inc() = (x := x + 1) }
```

- The class has an invariant  $x \geq 0$ , i.e., all the methods preserve it.
- Hence, when the class is used in the context of any client, the entire program will preserve the invariant.
- Again, information hiding is what is at play: The variable  $x$  is hidden from the clients.

# Relational parametricity

- Invariants and binary simulation relations are both instances of the same concept: *Relational parametricity*.
- Formulated by John Reynolds in 1983 for polymorphic lambda calculus.
- In the OOP context:

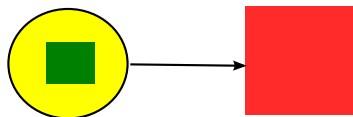


$$\text{client} : \forall_X F(X) \rightarrow K(X)$$

- The mathematical meaning of  $\forall$  says that all possible relations between potential representation types  $X$  will be preserved by client.
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$$\text{client} : \forall_X F(X) \rightarrow K(X)$$

$$\text{client} : (\exists_X F(X)) \rightarrow K$$

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## Section 2

# States and actions

- In 1998, I discovered that there were two orthogonal dimensions to modeling mutable storage:

states                  actions

State-invariants and state simulation relations may not be enough.

- [Reynolds, 1981] used a similar modeling too. Simpler state-only models later invented by Oles, Tennent and O’Hearn. Reynolds’s model was essentially “forgotten”.
- In the Formal Methods community, similar orthogonality was discovered in terms of *history Invariants*. Originally from Ina Jo [Scheid and Hostsberg, 1980-1992] and popularized by [Liskov and Wing, 1994] and used in Spec#.



- $x := x + 1$  satisfies a history invariant:

$$x \geq \mathbf{old}(x)$$

No matter how many times the command  $x := x + 1$  is run, the initial state and the final state will satisfy this property.

- It follows that

**while**  $x \leq 100$  **do**  $x := x + 1$

also satisfies the history invariant.

- Similar discussion as before applies: It does not matter what **while** does for the preservation of history invariants. User-defined combinators will also preserve it, if they are constant.

# Action invariants

- A slightly more general concept than history invariants.

$$P(a) \iff \forall n. a(n) \geq n$$

$P$  is a property of “actions,” i.e., state transformations.

- Another example:

$$Q(a) \iff \exists k. \forall n. a(n) = n + k$$

or

$$Q(a) \iff \forall n. \exists k. a(n) = n + k$$

- Binary action relations are similar:

$$a [R] b \iff \forall m, n. \exists k. a(n) = n + k \wedge b(m) = m - k$$

It is hard to see how to generalize traditional history invariants to binary relations.

# Where do action invariants come from?

- [O'Hearn and Tennent, 1993]: *Relational parametricity and local variables*.
  - Showed that the information hiding aspects of local variables can be modelled using relational parametricity (state-based relations).
  - [O'Hearn and Reynolds, 2000] used a variant using strict functions (linear functions) to get rid of some snapback effects. Proved it fully abstract for up to second-order function types.
- [Reddy, 1993]: *Global state considered unnecessary: Introduction to object-based semantics*.
  - Produced an event-based description of objects and classes, so that information hiding is directly represented.
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# O'Hearn-Tennent vs. Event-based

- Example in favour of the O'Hearn-Tennent model:

$$\llbracket x := x + 1; x := x + 1 \rrbracket \stackrel{?}{=} \llbracket x := x + 2 \rrbracket$$

- Example in favour of the Event-based model:

$$\begin{array}{l} \llbracket \text{class} \\ \quad \text{local Var[int] } x; \\ \quad \text{init } x := 0; \\ \quad \text{meth} \\ \quad \quad \{ \text{val}() = x, \\ \quad \quad \text{inc}() = (x := x + 1) \} \rrbracket \end{array} \stackrel{?}{=} \begin{array}{l} \llbracket \text{class} \\ \quad \text{local Var[int] } x; \\ \quad \text{init } x := 0; \\ \quad \text{meth} \\ \quad \quad \{ \text{val}() = -x, \\ \quad \quad \text{inc}() = (x := x - 1) \} \rrbracket \end{array}$$

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# O'Hearn-Tennent vs. Event-based

- The O'Hearn-Tennent approach is good for computation, bad for data.
- The Event-based approach is good for data, bad for computation.
- Is it possible to have the best of both worlds?
- Can we have external behavior of agents described in terms of events/traces, but the internal behavior as *extensional* state transformation?



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$$\langle Q, \Sigma, \alpha : \Sigma \rightarrow [Q \rightarrow Q] \rangle$$

- $Q$  is a set of states.
- $\Sigma$  is a set of events.
- $\alpha$  interprets events as state transformations.
- The O'Hearn-Tennent model focuses on  $Q$ .
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- Automata provide a framework to combine the two.

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# Transformation monoids

- Transformation monoids represent an “algebraic” version of semiautomata:

$$\langle Q, T \subseteq [Q \rightarrow Q] \rangle$$

- $Q$  is a set of states.
- $T$  is a submonoid of state transformations.
  - $[Q \rightarrow Q]$  is the set of state transformations.
  - Sequential composition is “multiplication”.
  - The identity transformation is the “unit”.
- The elements of  $T$  are thought of as “actions”.
  - More abstract variants of events.
  - Composable

# Section 3

## Examples

# Example 1: Counters (state-based)

- A state-based model of counter objects:

$$\langle Q = \text{Int}, q_0 = 0, \{ \text{val} : Q \rightarrow \text{Int} = \lambda n. n, \\ \text{inc} : Q \rightarrow Q = \lambda n. n + 1 \} \rangle$$

- An alternative model of counter objects:

$$\langle Q' = \text{Int}, q'_0 = 0, \{ \text{val}' : Q' \rightarrow \text{Int} = \lambda n. -n, \\ \text{inc}' : Q' \rightarrow Q' = \lambda n. n - 1 \} \rangle$$

- Their equivalence can be shown using a simulation relation:

$$\begin{array}{c} Q \\ \uparrow \\ R \\ \downarrow \\ Q' \end{array} \quad n [R] n' \iff n \geq 0 \wedge n' = -n$$

- The verification conditions are:

$$\text{val} [R \rightarrow \Delta_{\text{Int}}] \text{val}' \quad \text{inc} [R \rightarrow R] \text{inc}'$$

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$$\text{Int}^+ = \text{down closure of } \{ \lambda n. n + k \mid k \geq 0 \}$$

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$$\text{Int}^- = \text{down closure of } \{ \lambda n. n - k \mid k \geq 0 \}$$

- Their equivalence is shown using *two* relations:

$$\begin{array}{ccc} Q & T & \\ R_Q \updownarrow & R_T \updownarrow & n [R_Q] n' \iff n \geq 0 \wedge n' = -n \\ Q' & T' & a [R_T] a' \iff \forall n, n'. a(n) - n \simeq -(a(n') - n') \end{array}$$

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## Example 1: Counters (automata-based)

- In addition to the state sets ( $Q$ ), we also represent the allowed state transformations ( $T$ ), with some natural coherence conditions.
- The state change operations of the objects are of type  $T$ , not  $Q \rightarrow Q$ . So, one can only perform allowed state transformations.
- The coherence conditions ensure that we cannot “cheat.” New transformations can be made only by composing the allowed transformations.

# Interlude: Idealized Algol

- Reynolds's Idealized Algol is a simply typed lambda calculus (CBN) with base types for state manipulation:

**comm**    **exp** $[\delta]$     **val** $[\delta]$

where  $\delta$  ranges over “data” types.

- Sample constants:

<b>0</b>	:	<b>exp</b> $[\text{int}]$
<b>+</b>	:	<b>exp</b> $[\text{int}] \times \text{exp}[\text{int}] \rightarrow \text{exp}[\text{int}]$
<b>skip</b>	:	<b>comm</b>
<b>—; —</b>	:	<b>comm</b> $\times$ <b>comm</b> $\rightarrow$ <b>comm</b>
<b>diverge</b>	:	<b>comm</b>
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# Interlude: IA+

- IA+ extends Idealized Algol with classes.
- **cls**  $\theta$  - the *type* of classes that have instances of type  $\theta$ .
- Primitive class (constant):

$\text{Var}[\delta] : \mathbf{cls} \{ \text{get} : \mathbf{exp}[\delta], \text{put} : \mathbf{val}[\delta] \rightarrow \mathbf{comm} \}$

- Class definition (and its equivalent ML fragment):

**class** :  $\theta$                        $\lambda(). \mathbf{let} \ x : \theta = \mathbf{new}C()$   
  **local**  $C \ x;$                       **in**  $A; M$   
  **init**  $A;$   
  **meth**  $M$

- Class instantiation:

$\mathbf{new} \ C \ o. \ P(o)$

- Additional constants:

$\mathbf{:=}$             :  $\mathbf{var}[\delta] \times \mathbf{exp}[\delta] \rightarrow \mathbf{comm}$   
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**deref**  $: \mathbf{var}[\delta] \rightarrow \mathbf{exp}[\delta]$

# Interlude: IA+

- IA+ extends Idealized Algol with classes.
- **cls**  $\theta$  - the *type* of classes that have instances of type  $\theta$ .
- Primitive class (constant):

$\text{Var}[\delta] : \mathbf{cls} \{ \text{get} : \mathbf{exp}[\delta], \text{put} : \mathbf{val}[\delta] \rightarrow \mathbf{comm} \}$

- Class definition (and its equivalent ML fragment):

**class**  $: \theta$                        $\lambda(). \mathbf{let} \ x : \theta = \mathbf{new}C()$   
  **local**  $C \ x;$                       **in**  $A; M$   
  **init**  $A;$   
  **meth**  $M$

- Class instantiation:

**new**  $C \ o. P(o)$

- Additional constants:

$::= \quad : \mathbf{var}[\delta] \times \mathbf{exp}[\delta] \rightarrow \mathbf{comm}$   
**deref**  $: \mathbf{var}[\delta] \rightarrow \mathbf{exp}[\delta]$

```
class : { val : exp[int], inc : comm }  
  local Var[int] x;  
  init x := 0;  
  meth { val = deref x, inc = (x := (deref x) + 1) }
```

# “Awkward” Example [Pitts & Stark, 1998]

Example written in IA+ (Idealized Algol extended with classes):

```
C = class : { m : comm → comm }  
  local Var[int] x;  
  init x := 0;  
  meth { m = λc. x := 1; c; test(x = 1) }
```

$test(b) \triangleq$  **if** *b* **then skip else diverge**

- Does *m* terminate (assuming *c* terminates)?  
Equivalently, do we believe that *c* does not change *x*?
- Tommy Hacker says “yes”. *x* is a local variable of the class. So, *c* can't have access to it.
- What say you?

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  meth  $\{m = \lambda c. x := 1; c; \mathit{test}(x = 1)\}$ 
```

- It is not sound to say that  $c$  does not have “access” to  $x$ .
- Consider the following client:

```
new  $C$   $o$ . // create an instance of  $C$  and call it  $o$   
   $o.m$  ( $o.m$  skip)
```

- When  $o.m$  is called, the argument passed involves another call to  $o.m$ . So the argument  $c$  *can* change  $x$ .
- The **correct argument** says that the *the only change*  $c$  can make to  $x$  is to set it to 1. If it does that change, the test will still succeed.

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```

- We can formalize the correct argument by formulating a two part invariant:

$$\begin{aligned} P_Q(x) &\iff x = 0 \vee x = 1 \\ P_T(a) &\iff a \sqsubseteq (\lambda n. n) \vee a \sqsubseteq (\lambda n. 1) \end{aligned}$$

- We must show that the body of *m* preserves the two-part invariant, while *assuming* that the argument *c* preserves the two-part invariant.



# “Very awkward” Example: Dreyer, Neis, Birkedal, 2010

```
C = class : {  $m$  : comm  $\rightarrow$  comm }  
  local Var[int]  $x$ ;  
  init  $x := 0$ ;  
  meth {  $m = \lambda c. x := 0; c; x := 1; c; test(x = 1)$  }
```

- This is a twist on the “awkward” example, by introducing an additional assignment  $x := 0$  in  $m$ .
- This seems to suggest that we should enlarge the action invariant to include  $\lambda n. 0$ .
- No need. The old invariant still works.

$$\begin{aligned} P_Q(x) &\iff x = 0 \vee x = 1 \\ P_T(a) &\iff a \sqsubseteq (\lambda n. n) \vee a \sqsubseteq (\lambda n. 1) \end{aligned}$$

- The first call to  $c$  will either leave  $x$  unchanged or set it to 1. But, we don’t care either way.  $m$  will immediately overwrite  $x$  with 1. The second call to  $c$  is the same as before.

# “Very awkward” Example: Dreyer, Neis, Birkedal, 2010

```
 $C = \mathbf{class} : \{m : \mathbf{comm} \rightarrow \mathbf{comm}\}$   
  local Var[int]  $x$ ;  
  init  $x := 0$ ;  
  meth  $\{m = \lambda c. x := 0; c; x := 1; c; \mathit{test}(x = 1)\}$ 
```

- Dreyer et al. prove that  $m$  terminates (assuming  $c$  terminates), by using two separate kinds of transitions:
  - *Private transitions*, such as  $x := 0$ , which represent internal state transitions inside methods.
  - *Public transitions*, such as  $x := 1$ , which are visible to the callers.
- We don't find a need for any special treatment of “private transitions.” They are handled automatically by the normal parametricity reasoning.

## Section 4

# Semantic Overview

# Possible world semantics

- The semantics of Idealized Algol is given as a possible world semantics.
- $\mathbf{W}$  - a category of worlds (with relations), formally a *parametricity graph*.
  - The objects of  $\mathbf{W}$  represent *store shapes*.
  - Morphisms  $f : X \rightarrow W$  in  $\mathbf{W}$  represent the idea that  $X$  is a possible *future world* of  $W$ , typically a larger store than  $W$ .
- Types of the programming language  $\theta$  are interpreted as **functors** (with some technicalities):

$$[[\theta]] : \mathbf{W}^{\text{op}} \rightarrow \mathbf{CPO}$$

- Terms of the programming language are interpreted as **parametric transformations**:

$$x_1 : \theta_1, \dots, x_n : \theta_n \vdash M : \theta' \quad [[M]] : [[\vec{\theta}]] \rightarrow [[\theta']]$$

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# Possible world semantics - contd

- Denote  $[[\theta]]$  by  $F$ .
- For each world  $W$ ,  $F(W)$  is the set of meanings of type  $\theta$  for store  $W$ .
- Morphisms, relations and squares are mapped as well:

$$\begin{array}{ccc} X & & F(X) \\ \downarrow f & \mapsto & \uparrow F(f) \\ W & & F(W) \end{array}$$

$$\begin{array}{ccc} X & & F(X) \\ \downarrow R & \mapsto & \downarrow F(R) \\ X' & & F(X') \end{array}$$

$$\begin{array}{ccc} X & \xrightarrow{f} & W \\ \uparrow S & & \downarrow R \\ S & & W \\ \downarrow & & \downarrow \\ X' & \xrightarrow{f'} & W' \end{array} \mapsto \begin{array}{ccc} F(X) & \xleftarrow{F(f)} & F(W) \\ \uparrow F(S) & & \downarrow F(R) \\ F(S) & & F(W) \\ \downarrow & & \downarrow \\ F(X') & \xleftarrow{F(f')} & F(W') \end{array}$$

- The meaning of a term is a uniform family of functions, preserving all possible relations between store shapes:

$$\begin{array}{ccccc} X & & \llbracket \vec{\theta} \rrbracket(X) & \xrightarrow{\llbracket M \rrbracket_X} & \llbracket \theta' \rrbracket(X) \\ \updownarrow R & & \updownarrow \llbracket \vec{\theta} \rrbracket(R) & & \updownarrow \llbracket \theta' \rrbracket(R) \\ X' & & \llbracket \vec{\theta} \rrbracket(X') & \xrightarrow{\llbracket M \rrbracket_{X'}} & \llbracket \theta' \rrbracket(X') \end{array}$$

- The uniformity property says that the meanings of terms act the same way for all store shapes.

# Possible world semantics - contd

- The meanings of types have this form:

$$\llbracket \mathbf{comm} \rrbracket(W) = \dots$$

$$\llbracket \mathbf{exp}[\delta] \rrbracket(W) = \dots$$

$$\llbracket \mathbf{val}[\delta] \rrbracket(W) = \llbracket \delta \rrbracket$$

$$\llbracket \theta_1 \times \theta_2 \rrbracket(W) = \llbracket \theta_1 \rrbracket(W) \times \llbracket \theta_2 \rrbracket(W)$$

$$\llbracket \theta \rightarrow \theta' \rrbracket(W) = \forall h: X \rightarrow W \llbracket \theta \rrbracket(X) \rightarrow \llbracket \theta' \rrbracket(X)$$

$$\llbracket \mathbf{cls} \theta \rrbracket(W) = \exists Z (Q_Z)_\perp \times \llbracket \theta \rrbracket(Z)$$

- Note the correspondence with the counter classes seen earlier:

$$\langle Q = \mathit{Int}, T = \mathit{Int}^+, q_0 = 0, \{ \mathit{val} : Q \rightarrow \mathit{Int} = \lambda n. n, \\ \mathit{inc} : T = \lambda n. n + 1 \} \rangle$$

$$\mathit{Int}^+ = \text{down closure of } \{ \lambda n. n + k \mid k \geq 0 \}$$

- We use automata-theoretic ideas to define the possible worlds **W** and the interpretation of the base types **comm** and **exp**.



# Possible world semantics - contd

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- We use automata-theoretic ideas to define the possible worlds **W** and the interpretation of the base types **comm** and **exp**.

# Semantics of types

- The meanings of types have this form:

$$\llbracket \mathbf{comm} \rrbracket(W) = \mathcal{T}_W$$

$$\llbracket \mathbf{exp}[\delta] \rrbracket(W) = [Q_W \rightarrow \llbracket \delta \rrbracket]$$

$$\llbracket \mathbf{val}[\delta] \rrbracket(W) = \llbracket \delta \rrbracket$$

$$\llbracket \theta_1 \times \theta_2 \rrbracket(W) = \llbracket \theta_1 \rrbracket(W) \rightarrow \llbracket \theta_2 \rrbracket(W)$$

$$\llbracket \theta \rightarrow \theta' \rrbracket(W) = \forall h: X \rightarrow W \llbracket \theta \rrbracket(X) \rightarrow \llbracket \theta' \rrbracket(X)$$

$$\llbracket \mathbf{cls} \theta \rrbracket(W) = \exists Z (Q_Z)_\perp \times \llbracket \theta \rrbracket(Z)$$

- Note that the meanings of commands are the *allowed* transformations of the store (an automaton).
- The corresponding relational actions are as expected.  
 $\llbracket \mathbf{comm} \rrbracket(R) = R_T$ .  $\llbracket \mathbf{exp}[\delta] \rrbracket(R) = [R_Q \rightarrow \Delta_{\llbracket \delta \rrbracket}]$ .

# Semantics of primitives

$$\text{cond}^E : \text{EXP}_{\text{Bool}} \times \text{EXP}_\delta \times \text{EXP}_\delta \rightarrow \text{EXP}_\delta$$
$$\text{cond}_W^E(e, e_1, e_2) = \lambda s. (\lambda v. v \rightarrow e_1(s); e_2(s))^*(e(s))$$
$$\text{cond}^C : \text{EXP}_{\text{Bool}} \times \text{COMM} \times \text{COMM} \rightarrow \text{COMM}$$
$$\text{cond}_W^C(e, a, b) = \text{read}_W \lambda s. (\lambda v. v \rightarrow a; b)^*(e(s))$$
$$\text{deref} : \text{VAR}_\delta \rightarrow \text{EXP}_\delta$$
$$\text{deref}_W(e, a) = e$$
$$\text{assign} : \text{VAR}_\delta \times \text{EXP}_\delta \rightarrow \text{COMM}$$
$$\text{assign}_W((d, a), e) = \text{read}_W \lambda s. a^*(e(s))$$
$$\text{Var}[\delta] : 1 \rightarrow \text{CLS } \text{VAR}_\delta$$
$$\text{Var}[\delta]_W(*) = \langle V, \text{init}_\delta, \text{mkvar} \rangle$$
$$\text{where } V = (\delta, T(\delta)) \quad \text{mkvar} = (\lambda n. n, \lambda k. \lambda n. k)$$
$$\text{newvar} : (\text{VAR}_\delta \Rightarrow \text{COMM}) \rightarrow \text{COMM}$$
$$\text{newvar}_W(p) = (\lambda s. (s, \text{init}_\delta)) \cdot p[\pi_1](\text{mkvar} \uparrow_V^{W*V}) \cdot (\lambda(s, n). s)$$

- **Theorem:** The semantics is parametric.
- This implies the soundness of the reasoning principles with two-part simulation relations and two-part invariants.
- Several representation results without divergence, e.g.,

$$\llbracket \mathbf{comm} \rightarrow \mathbf{comm} \rrbracket(\mathbf{1}) \cong \mathit{Nat}$$

- Some representation results with divergence, especially for passive types:

$$\llbracket \mathbf{comm} \rightarrow \mathbf{exp}[\delta] \rrbracket(W) \cong \llbracket \mathbf{exp}[\delta] \rrbracket(W)$$

# Section 5

## Conclusion

# Summary

- We made a small beginning to bridge the gap between state-based (Scott-Strachey) and event-based (Milner-Hoare) paradigms in semantics.
- Automata seem to provide the right structure to capture the intuitions about “agents” and “objects” that have internal structure and external behaviour.
- This seems to be quite worthwhile exercise as it gives simple reasoning principles to prove equivalences that were heretofore difficult to prove using denotational methods.

- Partial functions vs. strict functions.
- Weaken the Reynolds diagonal.  
Treat reading as a separate action.
- Call by value.
- Concurrency.
- Higher-order state.

# Further work - Applications

- Heap storage.
- Programming logics (Hoare logic, specification logic, separation logic).
- Rely-guarantee and deny-guarantee reasoning